



Optimization of Seismic Response in Tall Buildings Using Structural Dampers

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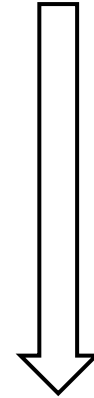
Outline / Agenda :

- Introduction
- Methodology
- Case Studies
- Comparison: BEM (PLPAK) vs FEM (ETABS)
- Comparison between MR Dampers and Static Dampers

- **Introduction**

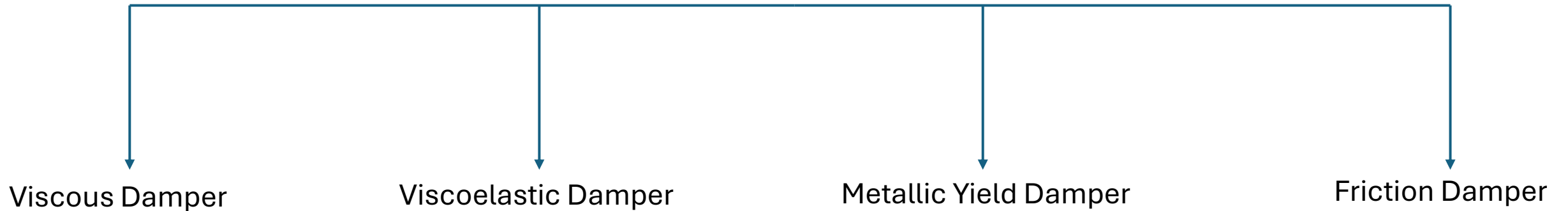
- Seismic design of high-rise buildings remains challenging
- International design codes lack explicit rules for:
 - Required number of dampers
 - Optimal damper distribution along building height
- Damper design is commonly based on:
 - Trial-and-error procedures
- This research proposes a **model-independent framework** for damper integration
- Material-based (static) dampers are incorporated by:
 - Modifying global stiffness and damping matrices
- An optimization approach based on:
 - Influence matrices
 - Integer linear programmingis used to determine the **optimal number and location of dampers**
- Targeted performance objectives:
 - Reduction in displacement
 - Reduction in inter-story drift
 - Reduction in floor acceleration

Energy Dissipation Systems (Vibration Control Systems)



Static Damper

Passive Energy Dissipation Devices



$$F(t) = k_{\text{tot}} x(t) + c_{\text{tot}} v(t) + m \ddot{x}(t)$$

Viscous Damper

- Relies on the viscosity of a fluid passing through an orifice.
- Provides **damping only** .(erutcurts eht ot ssenffits lanoitidda on)

C



Viscoelastic Damper

- Contains a material with both **elastic and viscous**.seitreporp
- Provides **damping + some additional stiffness**.

C & K



Metallic Yield Damper

- Dissipates energy through the **plastic deformation of metals** (steel plates or braces).
- Provides **both stiffness and damping**.

C & K



Friction Damper

- Relies on **friction between metallic surfaces**.
- Provides **mainly damping**, and sometimes **additional stiffness** depending on the design.

C & K



- **Methodology**

Objective:

Develop a user-friendly tool inside PLPAK (BEM) to incorporate static dampers by modifying the global system matrices

Direct modification of:

- ✓ Global stiffness matrix [K]
- ✓ Global damping matrix [C]

Features of the Tool:

- ✓ Control over the **number of dampers**.
- ✓ Define **orientation** (horizontal / vertical).
- ✓ Select **specific floors** for damper installation.
- ✓ Real-time **3D visualization** of dampers in the structural model.

Validation:

- ✓ Comparative analysis with **ETABS (FEM)**.

		6			5			4			3			2			1		
		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
6	1	2.33E+02	8.48E-09	-1.16E-03	-2.48E+02	-8.01E-09	1.17E-03	2.20E+01	-3.15E-10	5.52E-05	-4.73E+00	3.26E-10	-8.86E-05	1.06E+00	-3.34E-10	3.40E-05	-2.12E-01	-6.48E-11	-1.39E-05
	2	8.48E-09	3.27E+01	3.73E-08	-7.86E-09	-4.83E+01	-3.43E-08	-3.99E-10	2.20E+01	-2.01E-09	3.23E-10	-4.73E+00	1.43E-09	-3.60E-10	1.06E+00	-1.64E-09	-8.47E-11	-2.12E-01	-3.97E-10
	3	-1.16E-03	3.73E-08	9.65E+02	1.17E-03	-3.41E-08	-1.52E+03	5.56E-05	-2.11E-09	7.41E+02	-8.86E-05	1.43E-09	-1.66E+02	3.41E-05	-1.66E-09	3.73E+01	-1.38E-05	-4.18E-10	-8.81E+00
	4	-2.48E+02	-7.86E-09	1.17E-03	5.15E+02	1.21E-08	-1.88E-03	-2.89E+02	-3.08E-09	4.94E-04	3.07E+01	-2.00E-09	3.46E-04	-6.69E+00	1.11E-09	-1.81E-04	1.51E+00	-3.60E-10	6.86E-05
5	5	-8.01E-09	-4.83E+01	-3.41E-08	1.21E-08	1.15E+02	5.03E-08	-3.03E-09	-8.87E+01	-1.08E-08	-1.98E-09	3.07E+01	-9.64E-09	1.14E-09	-6.69E+00	5.21E-09	-3.32E-10	1.51E+00	-1.59E-09
	6	1.17E-03	-3.43E-08	-1.52E+03	-1.88E-03	5.03E-08	3.64E+03	4.94E-04	-1.08E-08	-2.92E+03	3.45E-04	-9.62E-09	1.06E+03	-1.81E-04	5.25E-09	-2.37E+02	6.84E-05	-1.56E-09	5.59E+01
	7	2.20E+01	-3.99E-10	5.56E-05	-2.89E+02	-3.03E-09	4.94E-04	5.37E+02	6.53E-09	-1.05E-03	-2.94E+02	-1.44E-09	2.32E-04	3.19E+01	-2.56E-09	4.24E-04	-7.23E+00	1.30E-09	-2.21E-04
	8	-3.15E-10	2.20E+01	-2.11E-09	-3.08E-09	-8.87E+01	-1.08E-08	6.53E-09	1.37E+02	2.44E-08	-1.45E-09	-9.36E+01	-3.25E-09	-2.57E-09	3.19E+01	-1.24E-08	1.29E-09	-7.23E+00	6.03E-09
4	9	5.52E-05	-2.01E-09	7.41E+02	4.94E-04	-1.08E-08	-2.92E+03	-1.05E-03	2.44E-08	4.45E+03	2.32E-04	-3.26E-09	-3.10E+03	4.24E-04	-1.24E-08	1.10E+03	-2.21E-04	6.02E-09	-2.59E+02
	10	-4.73E+00	3.23E-10	-8.86E-05	3.07E+01	-1.98E-09	3.45E-04	-2.94E+02	-1.45E-09	2.32E-04	5.38E+02	6.06E-09	-9.73E-04	-2.94E+02	-1.19E-09	1.93E-04	3.34E+01	-2.96E-09	4.92E-04
	11	3.26E-10	-4.73E+00	1.43E-09	-2.00E-09	3.07E+01	-9.62E-09	-1.44E-09	-9.36E+01	-3.26E-09	6.06E-09	1.38E+02	2.21E-08	-1.19E-09	-9.42E+01	-2.06E-09	-2.96E-09	3.34E+01	-1.42E-08
3	12	-8.86E-05	1.43E-09	-1.66E+02	3.46E-04	-9.64E-09	1.06E+03	2.32E-04	-3.25E-09	-3.10E+03	-9.73E-04	2.21E-08	4.49E+03	1.93E-04	-2.06E-09	-3.12E+03	4.92E-04	-1.42E-08	1.15E+03
	13	1.06E+00	-3.60E-10	3.41E-05	-6.69E+00	1.14E-09	-1.81E-04	3.19E+01	-2.57E-09	4.24E-04	-2.94E+02	-1.19E-09	1.93E-04	5.40E+02	5.64E-09	-9.05E-04	-3.01E+02	-1.07E-10	1.02E-05
	14	-3.34E-10	1.06E+00	-1.66E-09	1.11E-09	-6.69E+00	5.25E-09	-2.56E-09	3.19E+01	-1.24E-08	-1.19E-09	-9.42E+01	-2.06E-09	5.64E-09	1.40E+02	2.02E-08	-1.08E-10	-1.01E+02	2.97E-09
2	15	3.40E-05	-1.64E-09	3.73E+01	-1.81E-04	5.21E-09	-2.37E+02	4.24E-04	-1.24E-08	1.10E+03	1.93E-04	-2.06E-09	-3.12E+03	-9.05E-04	2.02E-08	4.55E+03	1.02E-05	2.97E-09	-3.36E+03
	16	-2.12E-01	-8.47E-11	-1.38E-05	1.51E+00	-3.32E-10	6.84E-05	-7.23E+00	1.29E-09	-2.21E-04	3.34E+01	-2.96E-09	4.92E-04	-3.01E+02	-1.08E-10	1.02E-05	3.70E+02	3.49E-09	-5.48E-04
1	17	-6.48E-11	-2.12E-01	-4.18E-10	-3.60E-10	1.51E+00	-1.56E-09	1.30E-09	-7.23E+00	6.02E-09	-2.96E-09	3.34E+01	-1.42E-08	-1.07E-10	-1.01E+02	2.97E-09	3.49E-09	1.70E+02	9.77E-09
	18	-1.39E-05	-3.97E-10	-8.81E+00	6.86E-05	-1.59E-09	5.59E+01	-2.21E-04	6.03E-09	-2.59E+02	4.92E-04	-1.42E-08	1.15E+03	1.02E-05	2.97E-09	-3.36E+03	-5.48E-04	9.77E-09	5.59E+03

$$C_{Add} = \begin{bmatrix} C_{Damper} & \cdots & -C_{Damper} \\ \vdots & \ddots & \vdots \\ -C_{Damper} & \cdots & C_{Damper} \end{bmatrix} \begin{matrix} U_{start} \\ \\ U_{end} \end{matrix}$$

$$K_{Add} = \begin{bmatrix} k_{Damper} & \cdots & -k_{Damper} \\ \vdots & \ddots & \vdots \\ -k_{Damper} & \cdots & k_{Damper} \end{bmatrix} \begin{matrix} U_{start} \\ \\ U_{end} \end{matrix}$$

Add this matrix between two degrees of freedom that are linked by damper in overall matrix to structure.

• Proposed Optimization Technique

The method aims to determine the optimal number of dampers on each floor to achieve a target structural response, particularly minimizing the displacement of the top floor under dynamic loading. The contribution of each damper to the floor displacements is quantified using an influence matrix. This matrix is generated by calculating the change in displacement resulting from adding a single damper at each floor, effectively capturing the effect of individual dampers on the overall structural response. These influence values are then used within the optimization model, which seeks to minimize the absolute difference between the actual top-floor displacement and the target displacement, while simultaneously minimizing the total number of dampers.

- New Response Calculation (Linear Model):

The new response R_k^{new} for any response type R at any floor k is a linear function of the initial response and the effect of the dampers ($I^R \times X$):

$$R_k^{new} = R_k^{actual} - \sum_{j=1}^n I_{kj}^R \cdot X_j$$

$$\begin{pmatrix} R_1^{new} \\ R_2^{new} \\ \vdots \\ R_n^{new} \end{pmatrix} = \begin{pmatrix} R_1^{actual} \\ R_2^{actual} \\ \vdots \\ R_n^{actual} \end{pmatrix} - \begin{pmatrix} I_{11}^R & I_{12}^R & \dots & I_{1n}^R \\ I_{21}^R & I_{22}^R & \dots & I_{2n}^R \\ \vdots & \vdots & \ddots & \vdots \\ I_{n1}^R & I_{n2}^R & \dots & I_{nn}^R \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{pmatrix}$$

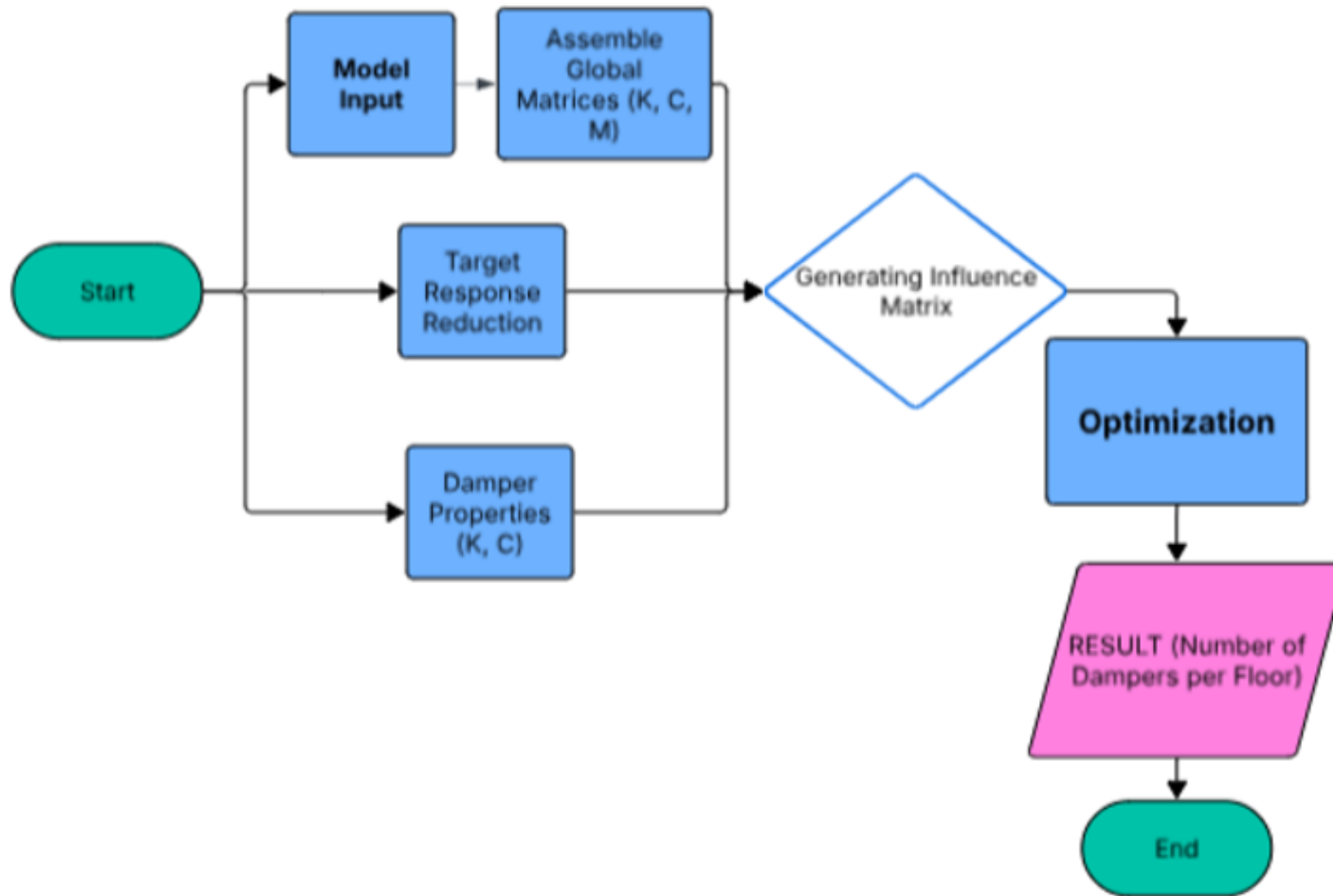
- Defining the Maximum (R_{new}^{max}):

$$\text{Constraint: } R_{new}^{max} \geq R_k^{actual} - \sum_{j=1}^n I_{kj}^R \cdot x_j \quad \rightarrow k = 1, 2, \dots, n \text{ for } R \in \{U, D, A\}$$

- Objective Function:

$$\text{Minimize: } Z = W_1 \cdot e + W_2 \cdot \sum_{i=1}^n x_i$$

Notation	Description	Type	Size/Dimension	Role in the Model
n	The total number of floors in the structure.	Constant	Scalar	Defines the size of vectors and matrices.
P	Required percentage reduction (e.g., 0.30 for 30%).	Constant	Scalar	Determines the value of R^{target}
x	Damper Design Vector (Decision Variables). Contains the number of dampers to be installed at each floor.	Integer Vector	n×1	The primary output (solution) of the optimization.
R_{actual}^{max}	Maximum Initial Response. The largest value found across all floors and all actual responses (U,D,A) before adding dampers.	Constant	Scalar	Used to calculate R^{target} .
R^{actual}	The actual initial response value (e.g., $U_{kactual}$, $D_{kactual}$, $A_{kactual}$) at floor k before damper installation.	Vector	n×1	Serves as the baseline for the new response calculation.
R^{target}	Relative Target Value. The target response the optimization aims to achieve: $R_{target} = (1 - P) \times R_{actual}^{max}$	Vector	n×1	The reference point for the deviation variable e.
R_{new}^{max}	Auxiliary Maximum Response Variable. The largest calculated response value ($\max R_k^{new}$) after the optimal dampers.	Variable	Scalar	Forced by constraints to equal the worst-case response, serving as the response metric in the objective.
I^R	Influence Coefficient Matrix for a specific response $R \in \{U, D, A\}$.	Matrix	n×n	Quantifies the linear effect of damper x_j on response R_k .
e	Auxiliary Deviation Variable. Represents the absolute difference	Variable	Scalar	$R_{new}^{max} - R^{target}$
W1	Weight coefficient for minimizing deviation (e).	Constant	Scalar	Assigned a high value (e.g., 10000) to prioritize matching the target.
W2	Weight coefficient for minimizing total dampers ($\sum x_i$).	Constant	Scalar	Assigned a low value (e.g., 1) to prioritize cost reduction after meeting the target.



Influence matrix

[illegible]

Actual displacement

[illegible]

Target displacement

[illegible]

Result - Optimal solution found

Objective value: 4.25600000
Enumerated nodes: 76
Total iterations: 808
Time (CPU seconds): 0.05
Time (Wallclock seconds): 0.05

Option for printingOptions changed from normal to all

Total time (CPU seconds): 0.05 (Wallclock seconds): 0.05

Optimal dampers distribution:

Floor 1: 0 dampers
Floor 2: 0 dampers
Floor 3: 2 dampers
Floor 4: 1 dampers
Floor 5: 0 dampers
Floor 6: 1 dampers
Floor 7: 0 dampers
Floor 8: 0 dampers
Floor 9: 0 dampers
Floor 10: 0 dampers

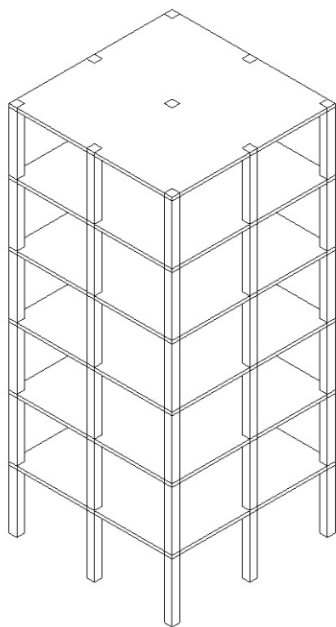
Total dampers = 4

Displacement at last floor: 0.01394030

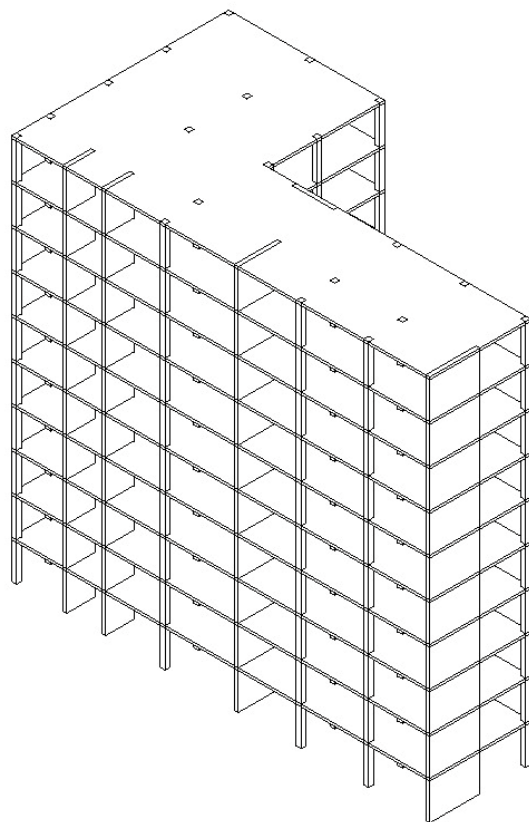
Target for last floor: 0.01391470

- **Case Studies**

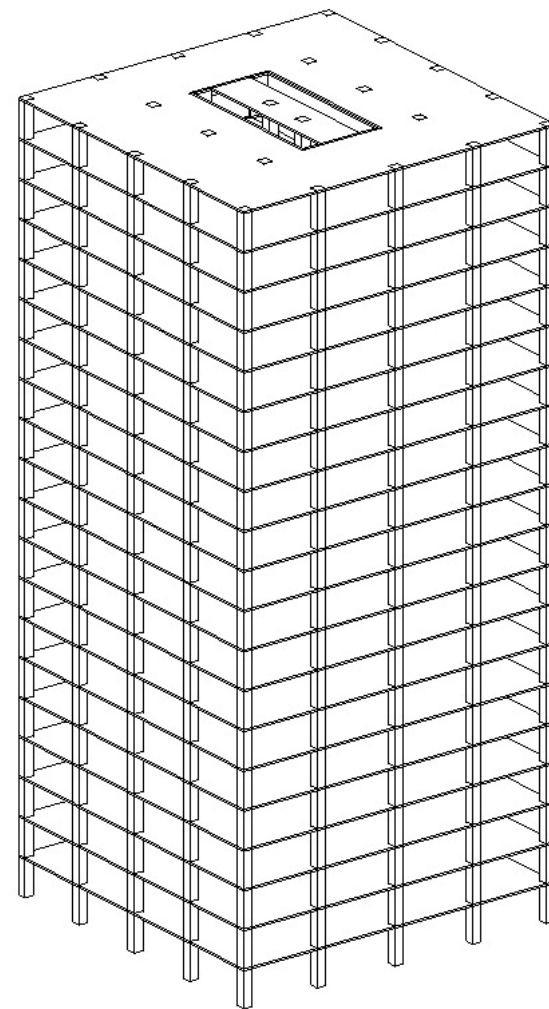
BEM (PLPAK)



Building 1: 6-story

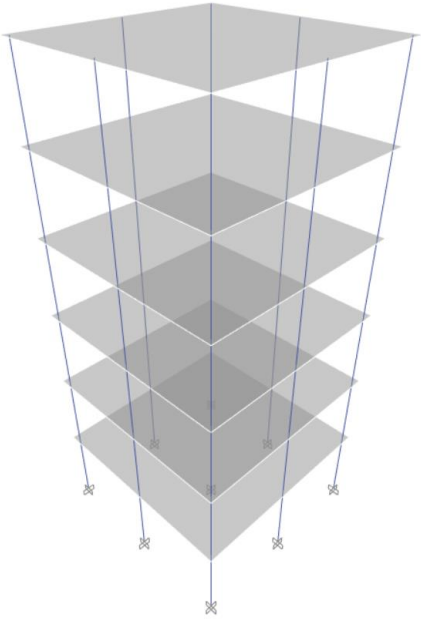


Building 2: 10-story

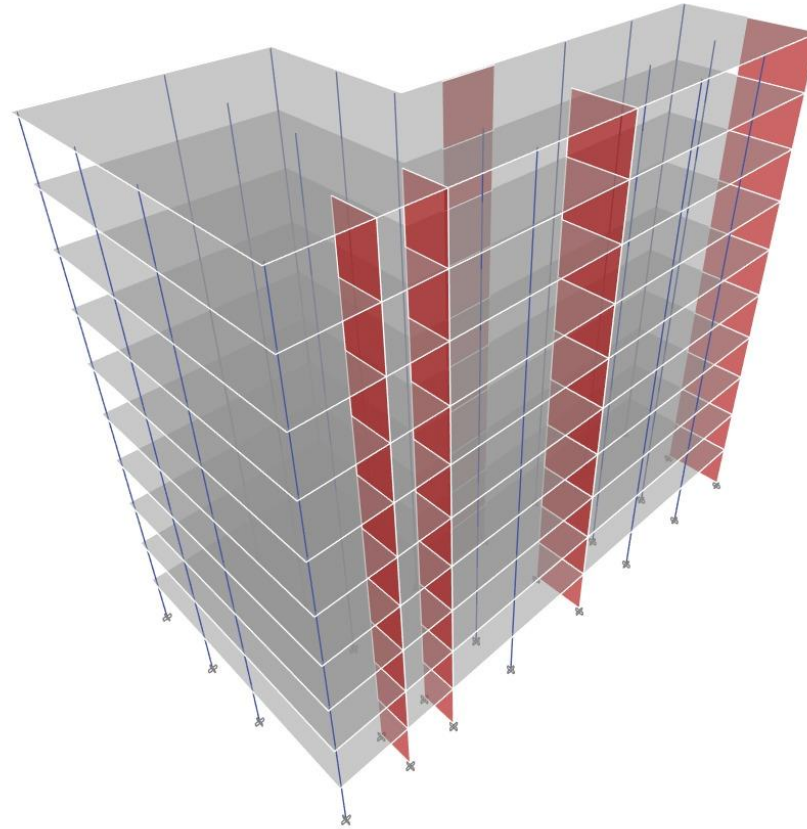


Building 3: 20-story

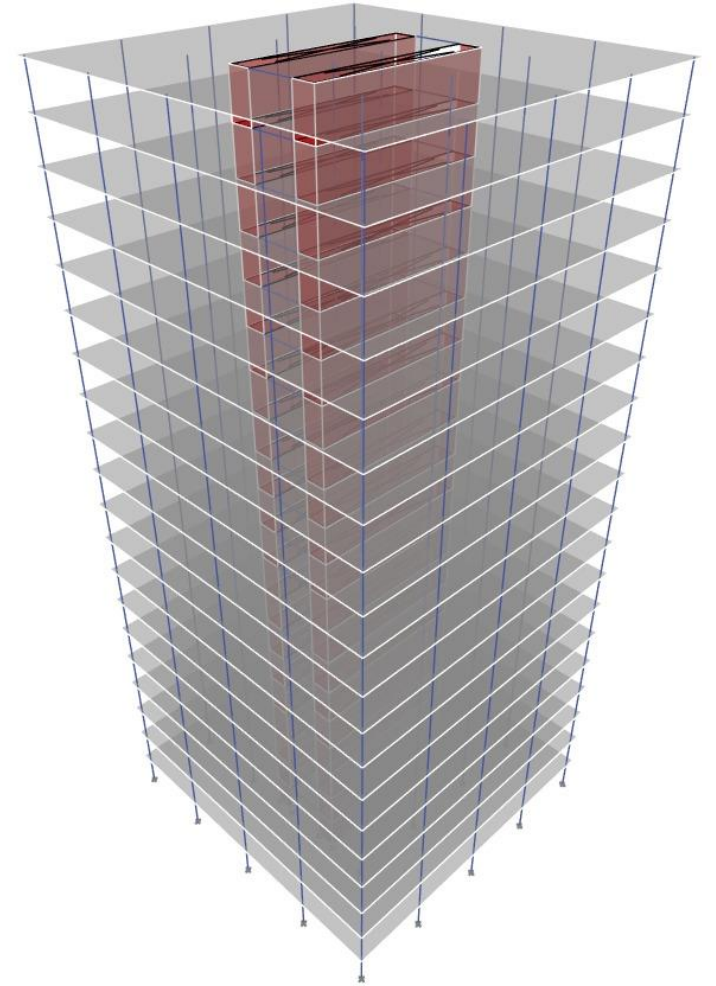
FEM (ETABS)



Building 1: 6-story



Building 2: 10-story



Building 3: 20-story

- **Comparison: BEM (PLPAK) vs FEM (ETABS)**

Building 1: 6-story

Dimension of slab = 10.5*10.5 m

Dimension of column = 500*500 mm

Thickness of slab = 200 mm

Spacing between column = 5 m

Story height = 4

Number of stories = 6

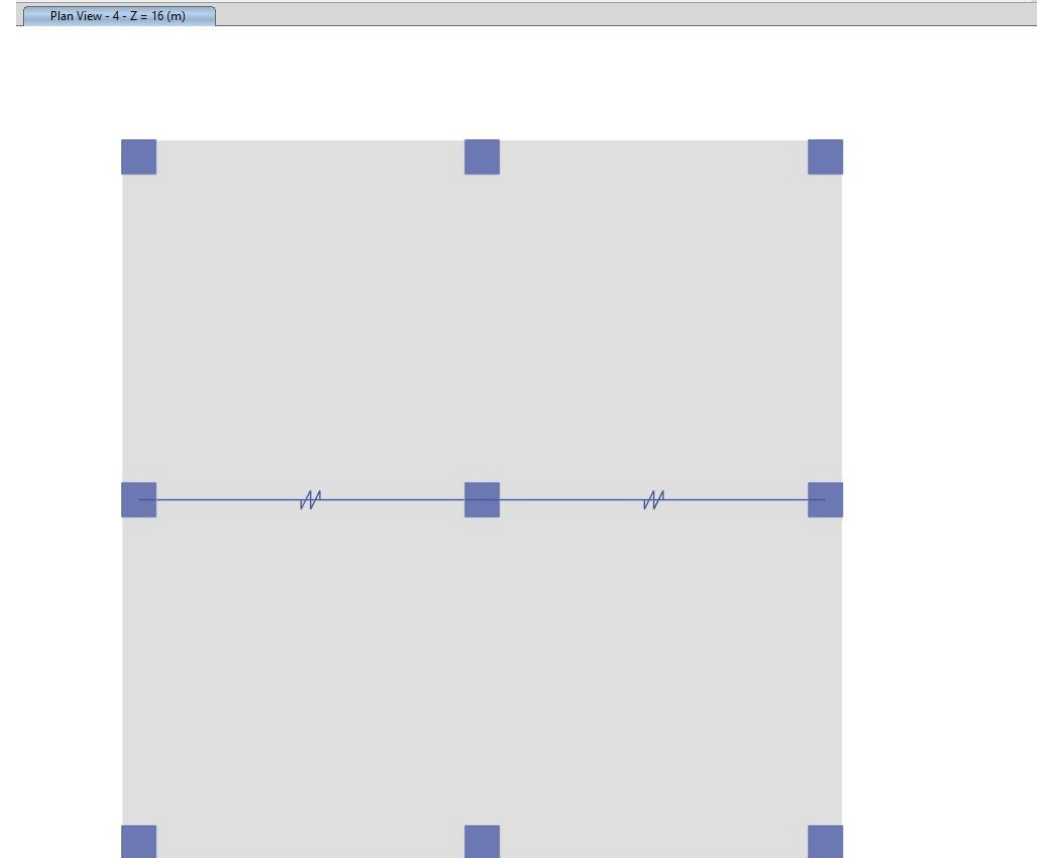
Damping ratio = 0.05

Rigid Diaphragm

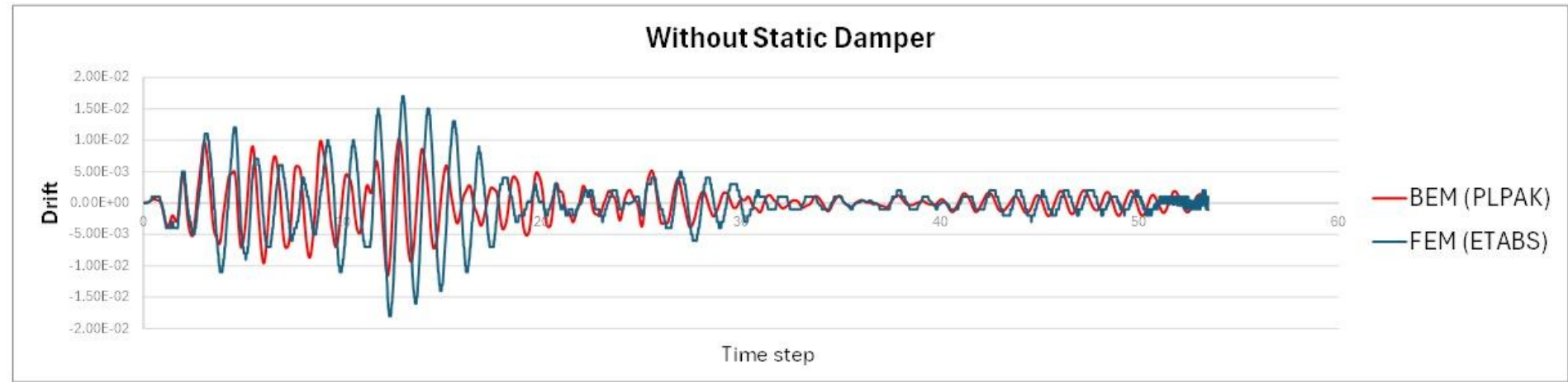
Static Damper: $C = 1000 \text{ KN} \cdot \text{s/m}$, $K=0 \text{ KN/m}$, $N=2$

Time History:

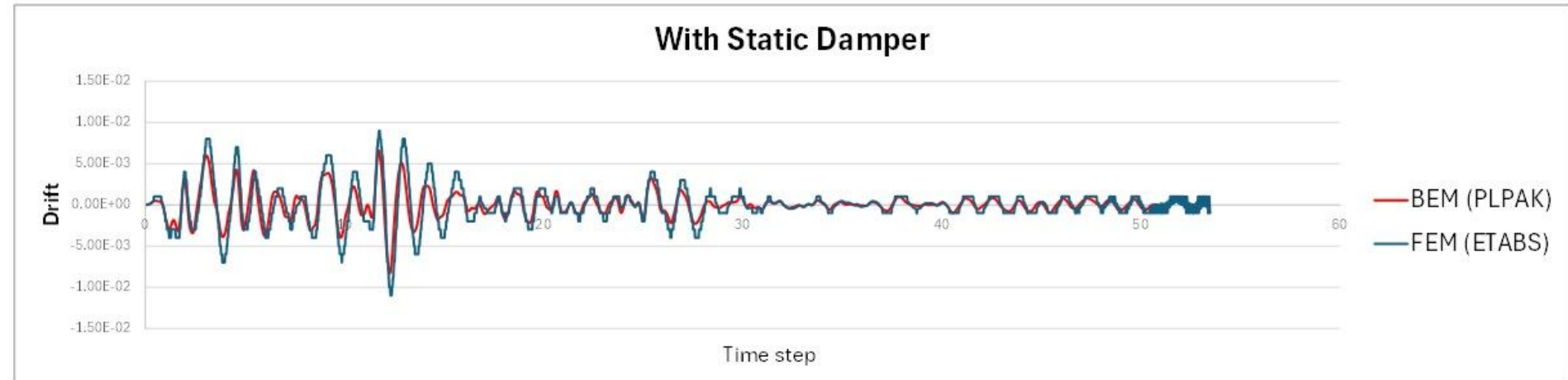
EL CENTRO EARTHQUAKE MAY 18, 1940
NORTH-SOUTH COMPONENT



Max drift FEM = 0.018 mm
Max drift BEM = 0.012 mm



Max drift FEM = 0.011 mm
Max drift BEM = 0.008 mm



$$\text{Reduction in ETABS} = \frac{18 - 11}{18} \times 100 = 38\%$$

$$\text{Reduction in PLPAK} = \frac{12 - 8}{12} \times 100 = 34\%$$

Building 2: 10-story

Dimension of column = 500*500 mm

Thickness of wall = 400 mm

Thickness of slab = 250 mm (Shell thick)

Story height = 4

Number of stories = 10

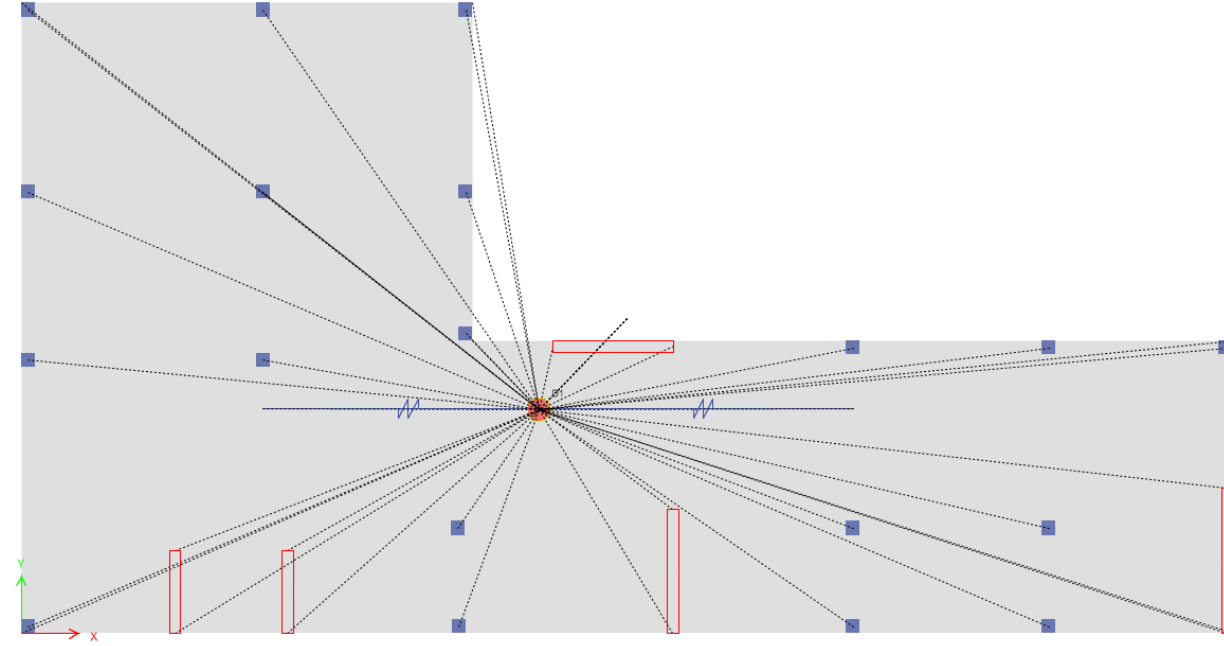
Damping ratio = 0.05

Rigid Diaphragm

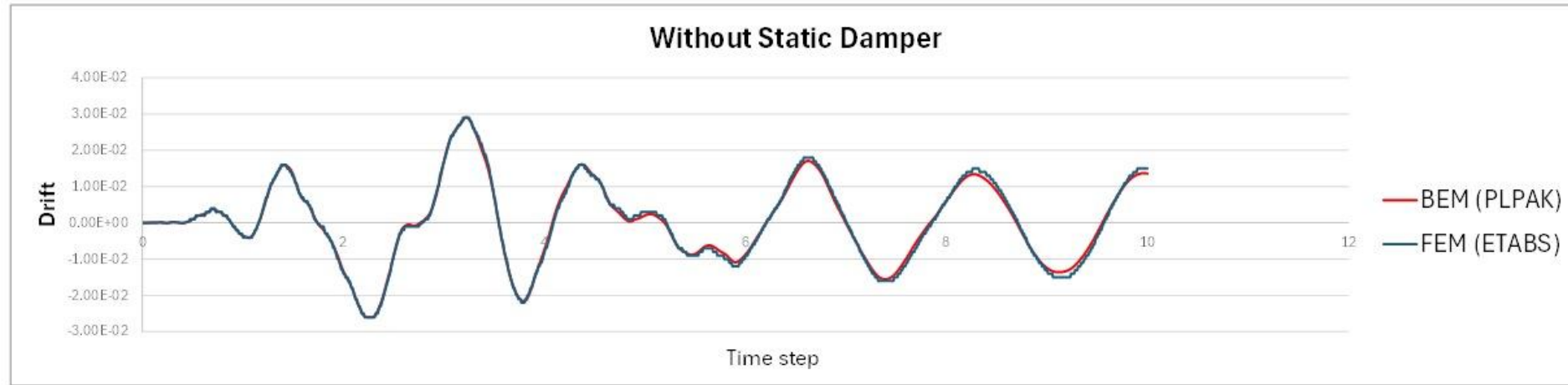
Static Damper: $C = 50000 \text{ KN} \cdot \text{s/m}$, $K = 10000 \text{ KN/m}$
 , $N = 2$

Time History:

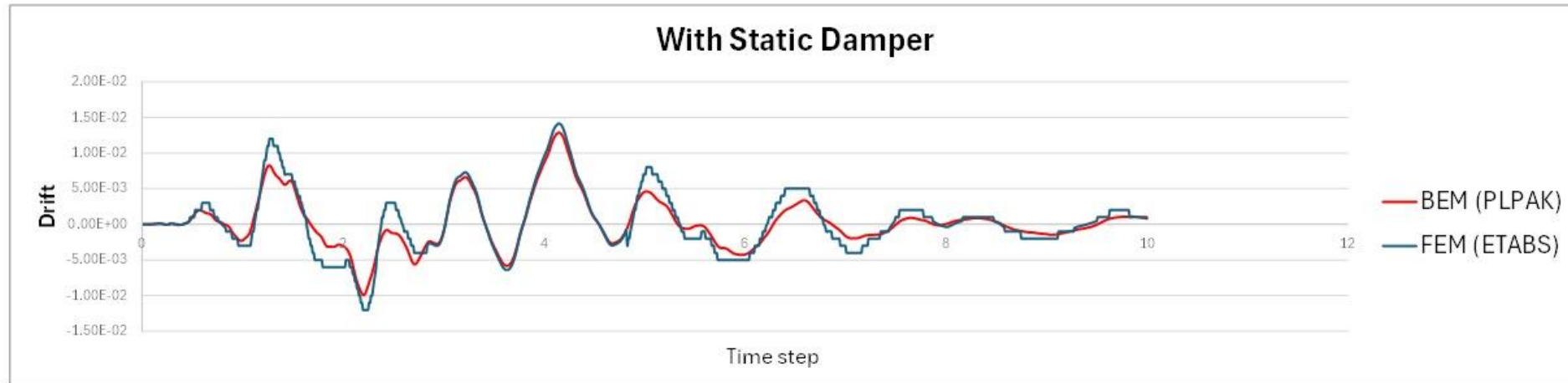
1992 Cairo Earthquake



Max drift FEM = 0.0292 mm
Max drift BEM = 0.029 mm



Max drift FEM = 0.014 mm
Max drift BEM = 0.0136 mm



$$\text{Reduction in ETABS} = \frac{29.1 - 14.1}{29.1} \times 100 = 52\%$$

$$\text{Reduction in PLPAK} = \frac{29 - 13.6}{29} \times 100 = 54\%$$

Building 3: 20-story

Dimension of column = 1000*1000 mm

Thickness of wall = 300 mm

Thickness of slab = 200 mm

Story height = 4

Number of stories = 20

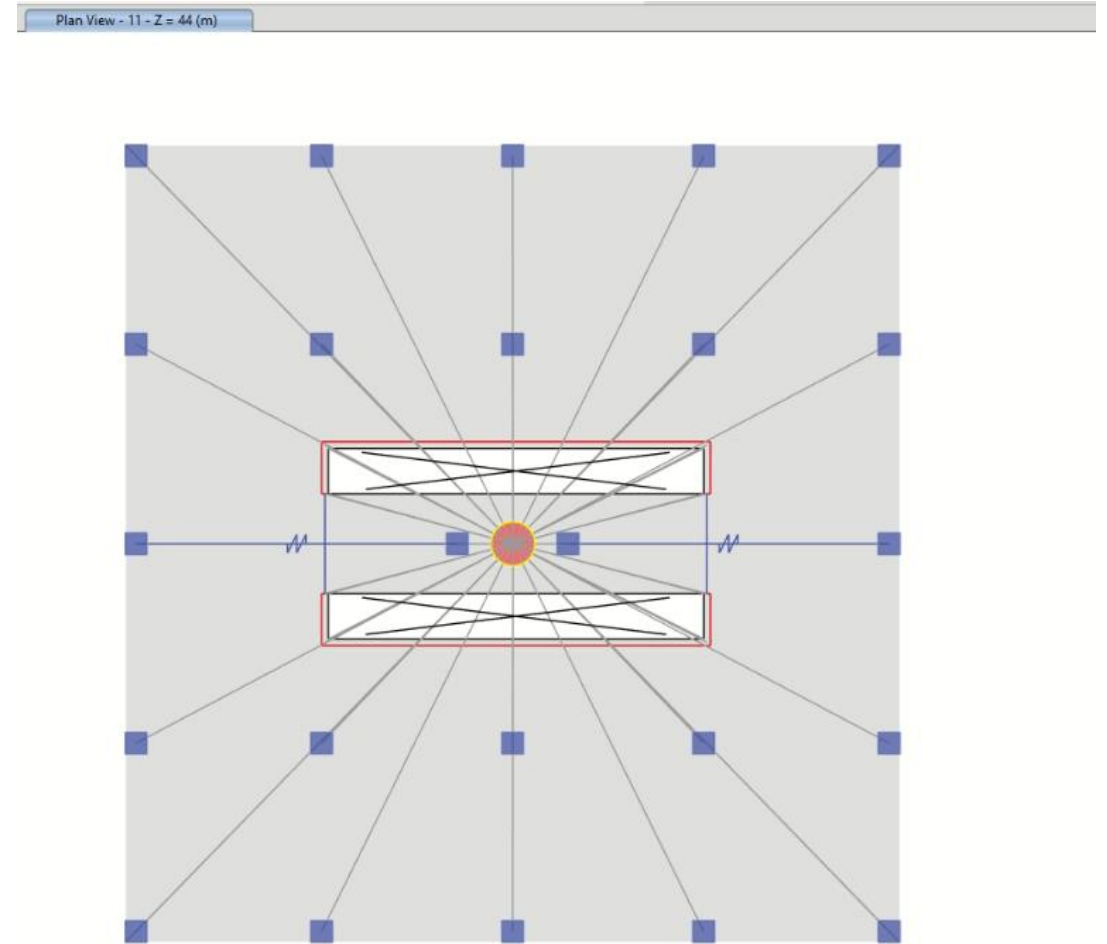
Damping ratio = 0.05

Rigid Diaphragm

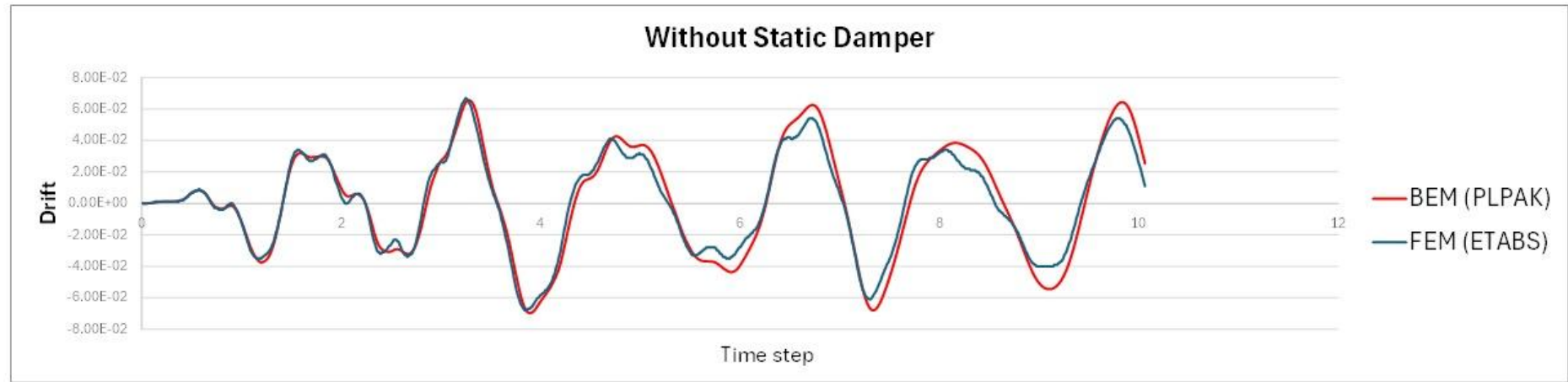
Static Damper: $C = 50000 \text{ KN} \cdot \text{s/m}$, $K = 25000 \text{ KN/m}$
 , $N = 2$

Time History:

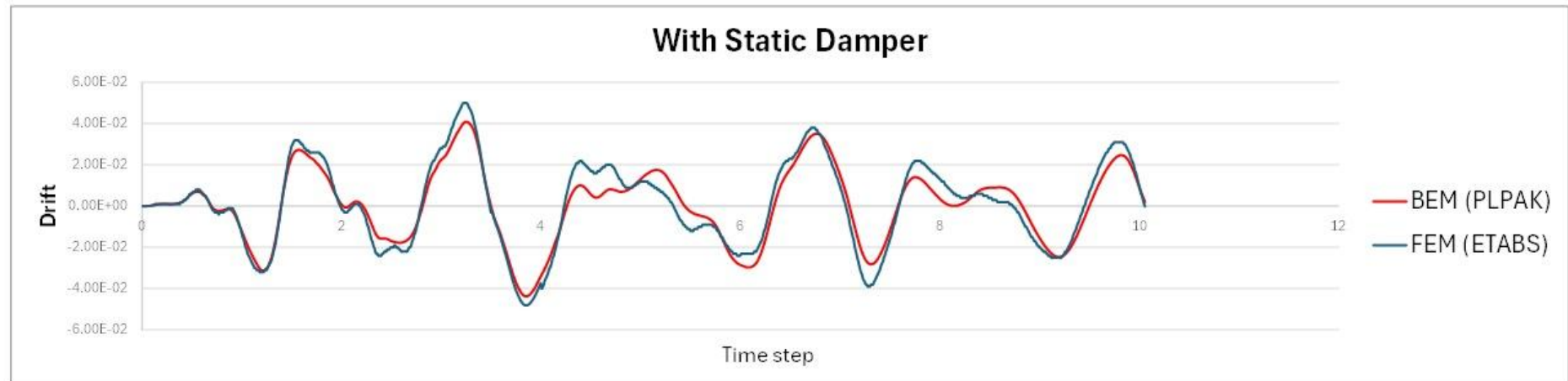
Analyses using EGY spectrum matched time histories



Max drift FEM = 0.070 mm
Max drift BEM = 0.068 mm



Max drift FEM = 0.050 mm
Max drift BEM = 0.045 mm

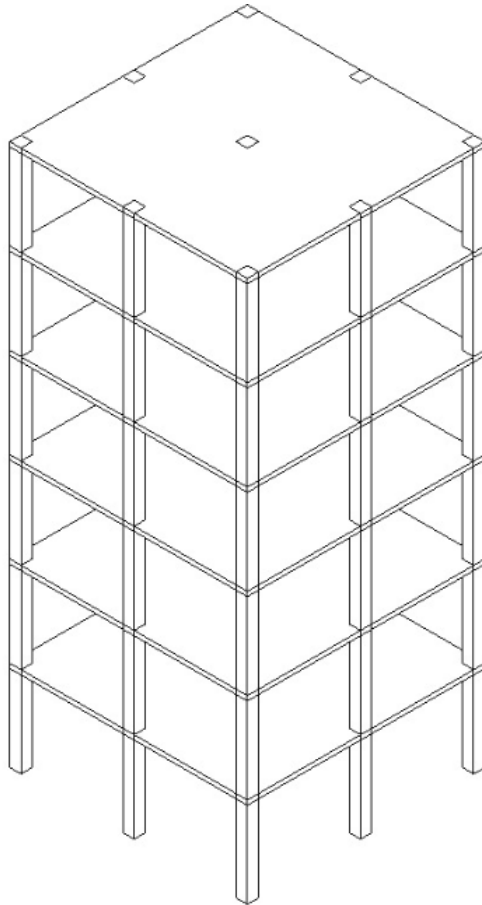


$$\text{Reduction in ETABS} = \frac{70 - 50}{70} \times 100 = 29\%$$

$$\text{Reduction in PLPAK} = \frac{68 - 45}{68} \times 100 = 34\%$$

• Comparison between MR Dampers and Static Dampers

Building 1: 6-story



Static Damper: $C = 1000 \text{ KN. s/m}$, $K=0 \text{ KN/m}$, $N=2$

MRDampersPanel

Design Mode Simulation Mode

1. Building Properties Directroy
Building Dynamic Folder: C:\Users\Fady\Desktop\New folder (2)\Dynam Select problem Directory
Number of Floors: 6

2. Loading Design EQ
☐ Choose EQ No. of steps: Time Step: Direction: Choose Design EQ
☒ Use Dynamic Solution EQ

3. Floors and Dampers factors R-Q
1. Set the upper and lower values for floor importance:
1 >> Max Importance
0 >> No Importance
Set all lower bound to zero
Set all Upper bound to one
2. Set the upper and lower values for damper action:
10E-7 >> Very strong action
10E-12 >> Strong action
10E-13 >> Mild action
less >> Weak action
Upper bound Lower Bound
10E-10 0.00

Has damper?	Floor	Importance Upper Bound	Importance Lower Bound
<input checked="" type="checkbox"/>	1	1	0
<input checked="" type="checkbox"/>	2	1	0
<input checked="" type="checkbox"/>	3	1	0
<input checked="" type="checkbox"/>	4	1	0
<input checked="" type="checkbox"/>	5	1	0
<input checked="" type="checkbox"/>	6	1	0

4. Target Control Parameter (J)
☐ Minimize Acceleration ☒ Minimize Displacement ☐ Minimize Inter-Story drift

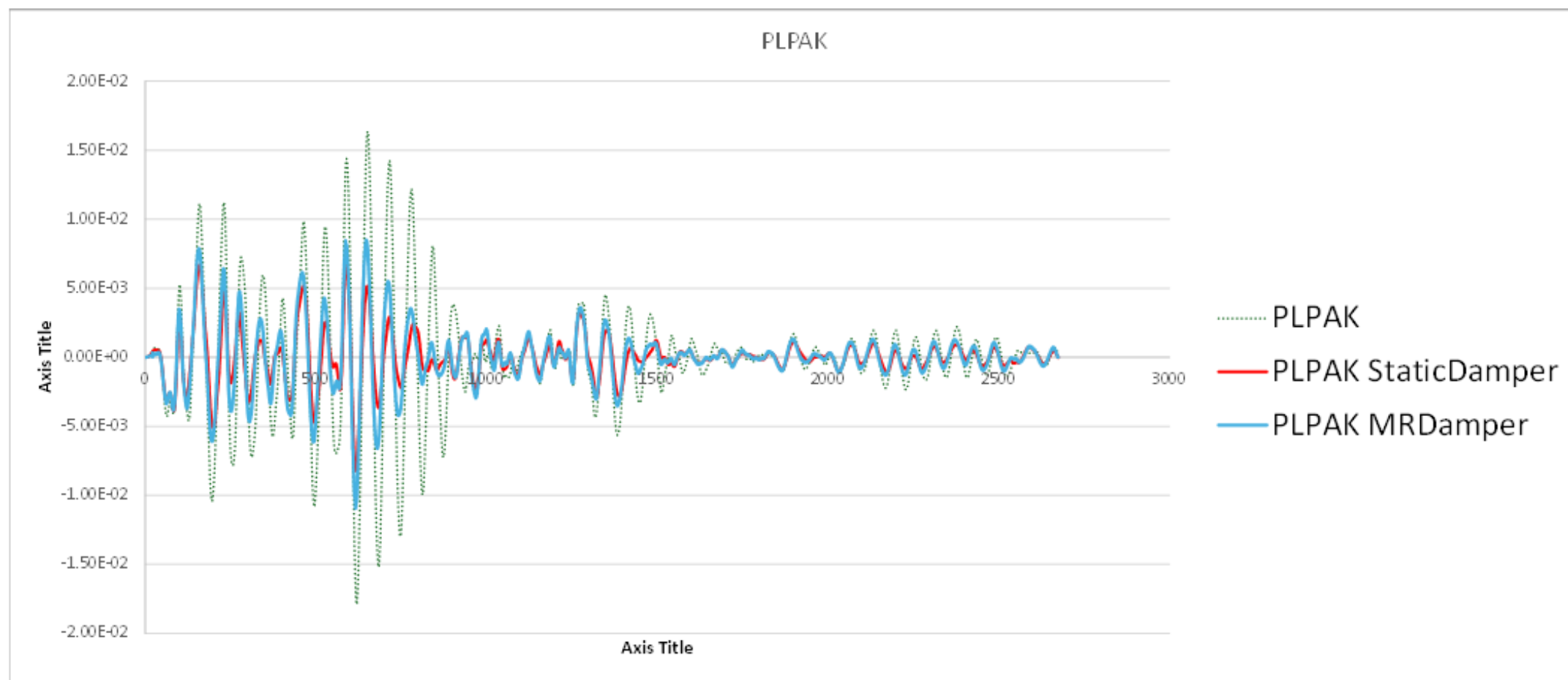
5. Damper Parameters

Parameter	Value
Capacity (KN)	1000
C0a	910
C0b	814.3
K0	0.002
C1a	8359.2
C1b	7482.9
K1	0.0097
X0	0.25
Alpha a	46.2
Alpha b	41.2
gamma	164

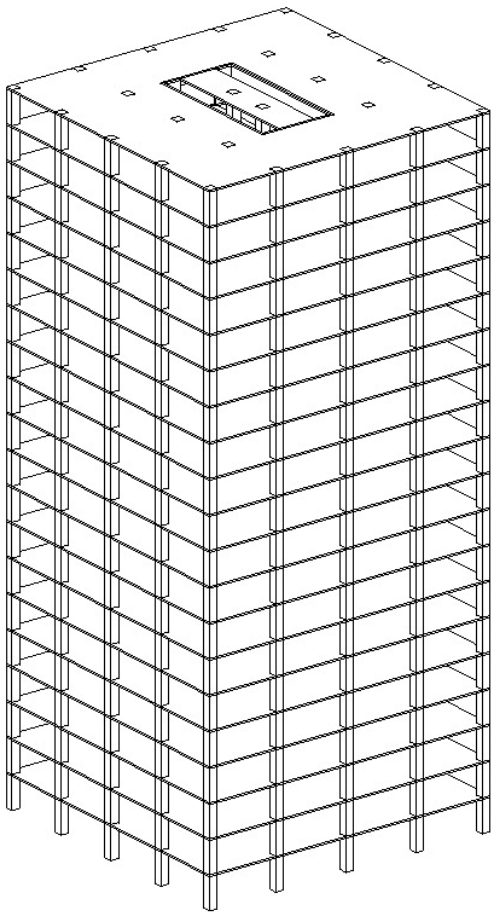
6. Optimization Parameters
Genetic algorithm Population: 100
Genetic algorithm Generation: 5
Swams Iterations: 2
Swams Particle Count: 2

Start Design Mode
Close

MR Damper: $C = 1000 \text{ KN. s/m}$, $N=1$



Building 3: 20-story



Static Damper: $C = 50000 \text{ KN. s/m}$, $K=25000 \text{ KN/m}$
 , $N=2$

MRDampPanel

Design ModeSimulation Mode

1. Building Properties Directroy

Building Dynamic Folder: C:\Users\Fady\Desktop\New folder\Dynamics

Select problem Directory

Number of Floors: 20

2. Loading Design EQ

Choose EQ

No. of steps:

Time Step:

Direction:

Choose Design EQ

Use Dynamic Solution EQ

C:\Users\Fady\Desktop\New folder\Dynamics\TH-DAT_EG SPEC

3. Floors and Dampers factors R-Q

1. Set the upper and lower values for floor importance:

1 >> Max Importance

0 >> No Importance

Set all lower bound to zero

Set all Upper bound to one

2. Set the upper and lower values for damper action:

10E-7 >> Very strong action

10E-12 >> Strong action

10E-13 >> Mild action

less >> Weak action

Upper bound Lower Bound

10E-10 0.00

4. Target Control Parameter (J)

Minimize Acceleration

Minimize Displacement

Minimize Inter-Story drift

5. Damper Parameters

Parameter	Value
Capacity (KN)	100000
C0a	11000
C0b	11400.
K0	0.002
C1a	83590.
C1b	74820.
K1	0.0097
X0	0.25
Alpha a	46.2
Alpha b	41.2
gamma	164

6. Optimization Parameters

Genetic algorithm Population: 50

Genetic algorithm Generation: 10

Swarms Iterations: 5

Swarms Particle Count: 2

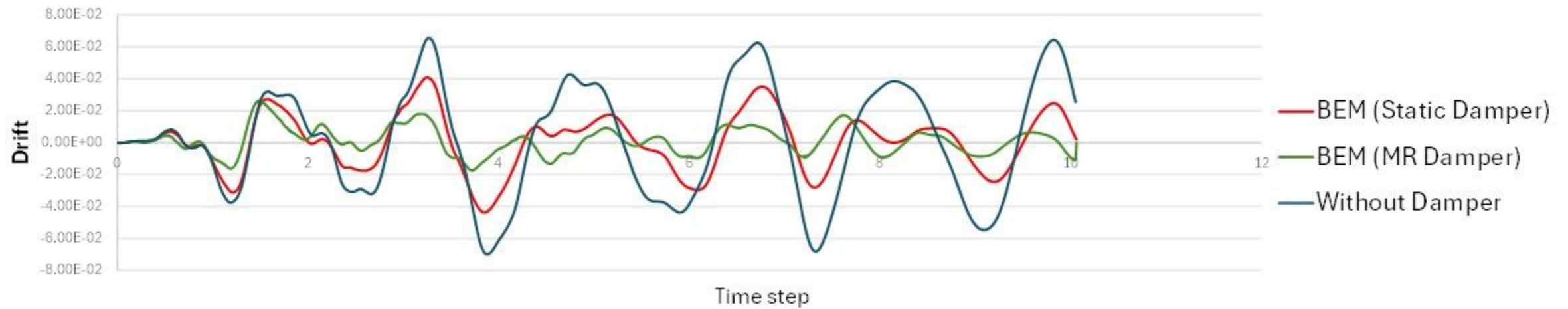
Start Design Mode

Close

Parameter	Value
Alpha b	41.2
gamma	164
beta	164
A	11107.
n	2
eta	100
Vmax (volt)	20
Vmin (volt)	0
active	0
CO	0

MR Damper: $C = 100000 \text{ KN. s/m}$, $N=1$

Comparison between MR Dampers and Static Dampers



Max drift Without Damper = 0.068 mm

Max drift BEM (Static Damper) = 0.045 mm

Max drift BEM (MR Damper) = 0.026 mm

